

Detecting Model Misspecification in Amortized Bayesian Inference with Neural Networks

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**Do you have a moment to talk about our
lord and savior**

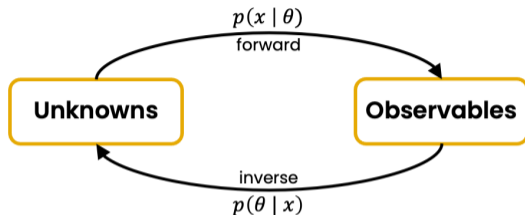
Do you have a moment to talk about our

lord and savior

Sir Thomas Bayes?



Inverse problems



Statistical modeling: Parameters θ

Data x

Epidemiology: Virus attributes

Infection curve (time series)

Image processing: Crisp image

Blurry image

Physics: Physical attributes

Graviational wave measurements

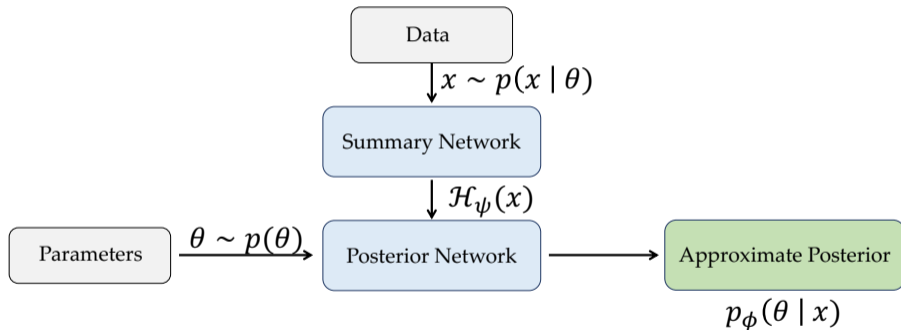
Bayesian inference

$$\underbrace{p(\boldsymbol{\theta} | \mathbf{x})}_{\text{inverse}} = \frac{\overbrace{p(\mathbf{x} | \boldsymbol{\theta}) p(\boldsymbol{\theta})}^{\text{forward}}}{\underbrace{\int p(\mathbf{x}, \boldsymbol{\theta}) d\boldsymbol{\theta}}_{= p(\mathbf{x})}}$$



Figure 1: [Maybe Thomas Bayes](#)

Neural posterior estimation (NPE)



NPE: Optimization objective

The analytic posterior $p(\boldsymbol{\theta} | \mathbf{x})$ and the approximated posterior $p_\phi(\boldsymbol{\theta} | \mathcal{H}_\psi(\mathbf{x}))$ on learned summary statistics $\mathcal{H}_\psi(\mathbf{x})$ shall match:

$$\begin{aligned}(\boldsymbol{\phi}^*, \boldsymbol{\psi}^*) &= \operatorname{argmin}_{\boldsymbol{\phi}, \boldsymbol{\psi}} \mathbb{E}_{p^*(\mathbf{x})} \left[\text{KL} \left(p(\boldsymbol{\theta} | \mathbf{x}) \parallel p_\phi(\boldsymbol{\theta} | \mathcal{H}_\psi(\mathbf{x})) \right) \right] \\ &= \operatorname{argmin}_{\boldsymbol{\phi}, \boldsymbol{\psi}} \mathbb{E}_{p^*(\mathbf{x})} \left[\mathbb{E}_{p(\boldsymbol{\theta} | \mathbf{x})} \left[-\log p_\phi(\boldsymbol{\theta} | \mathcal{H}_\psi(\mathbf{x})) \right] \right]\end{aligned}$$

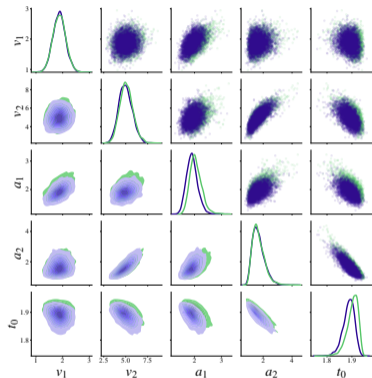
Out-of-distribution in NPE

Assume that the true data distribution $p^*(\mathbf{x})$ equals the simulated $p(\mathbf{x})$:

$$\begin{aligned}(\phi^*, \psi^*) &= \operatorname{argmin}_{\phi, \psi} \mathbb{E}_{p(\mathbf{x})} \left[\mathbb{E}_{p(\boldsymbol{\theta} | \mathbf{x})} \left[-\log p_{\phi}(\boldsymbol{\theta} | \mathcal{H}_{\psi}(\mathbf{x})) \right] \right] \\ &= \operatorname{argmin}_{\phi, \psi} \mathbb{E}_{p(\mathbf{x}, \boldsymbol{\theta})} \left[-\log p_{\phi}(\boldsymbol{\theta} | \mathcal{H}_{\psi}(\mathbf{x})) \right]\end{aligned}$$

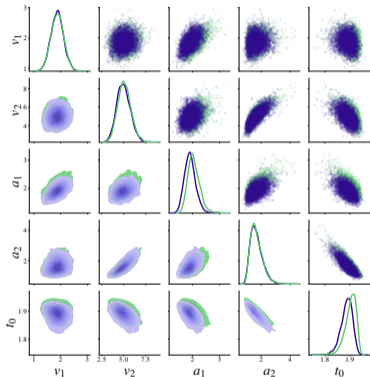
If $p^*(\mathbf{x}) \neq p(\mathbf{x})$, we optimize with respect to the wrong distribution.

What happens when MCMC and NPE encounter OOD data?

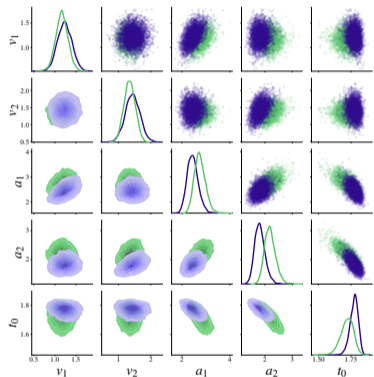


(a) well-specified: MCMC \approx NPE

What happens when MCMC and NPE encounter OOD data?

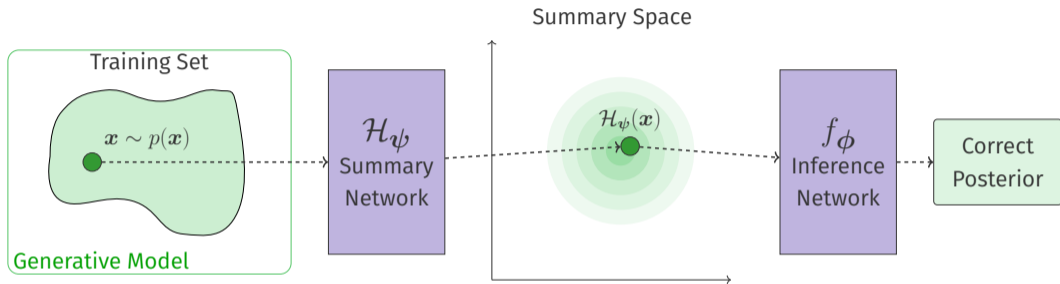


(a) well-specified: $\text{MCMC} \approx \text{NPE}$



(b) misspecified: $\text{MCMC} \neq \text{NPE}$

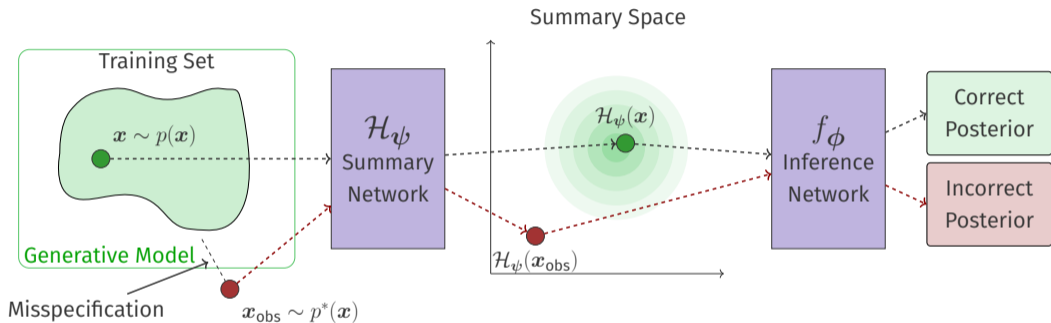
Structured summary statistics



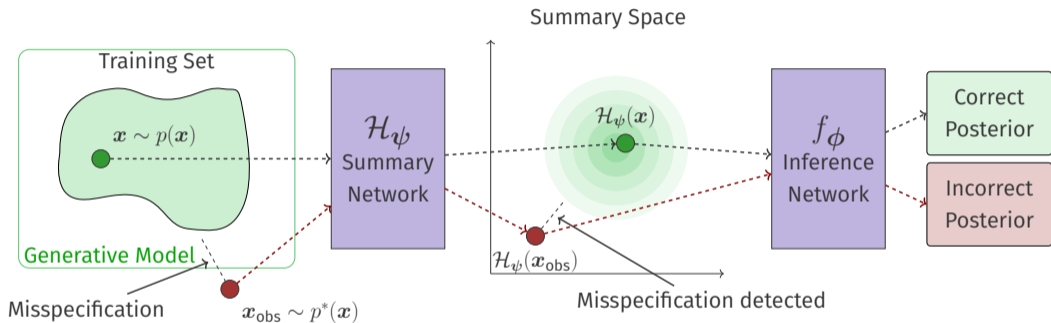
Optimize the summary network's output $\mathcal{H}_\psi(x)$ towards a unit Gaussian:

$$p(\mathcal{H}_\psi(x)) \approx \mathcal{N}(z \mid 0, \mathbb{I})$$

Detecting out-of-distribution data



Detecting out-of-distribution data



Detect via MMD between simulated $\mathcal{H}_\psi(x)$ and observed $\mathcal{H}_\psi(x_{\text{obs}})$

Experiment 1: Gaussian toy model

Gaussian: Setup

Recover mean vector μ of a 2-dimensional spherical Gaussian:

$$\begin{aligned}\mu &\sim \mathcal{N}(\mu \mid \mu_0, \tau_0 \mathbb{I}) \\ \mathbf{x}_k &\sim \mathcal{N}(\mathbf{x} \mid \mu, \tau \mathbb{I}) \quad \text{for } k = 1, \dots, K.\end{aligned}\tag{1}$$

Potential misspecifications:

- Prior location μ_0 and scale τ_0
- Likelihood scale τ
- Unmodeled noise

Gaussian: Perfect performance for well-specified model

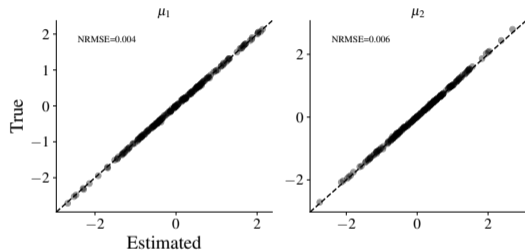


Figure 3: Well-specified case

Gaussian: Perfect performance for well-specified model

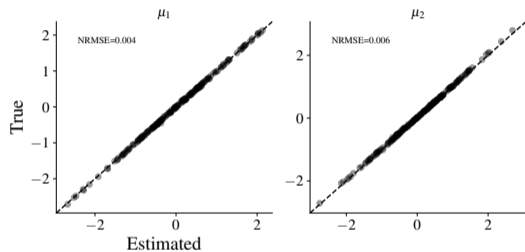


Figure 3: Well-specified case

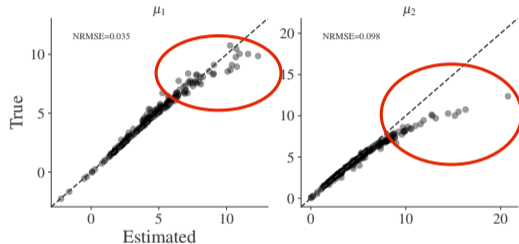
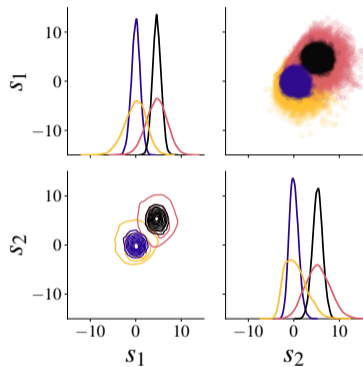


Figure 4: Prior misspecification: $\mu_0 = 2.5$

Gaussian: Inspecting the summary space

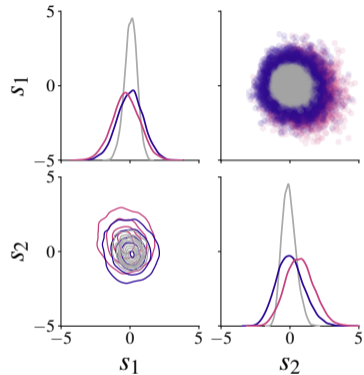


■ Prior location: $\mu_0 = 5$

■ Prior scale: $\tau_0 = 2.5$

■ Prior location and scale: $\mu_0 = 5, \tau_0 = 2.5$

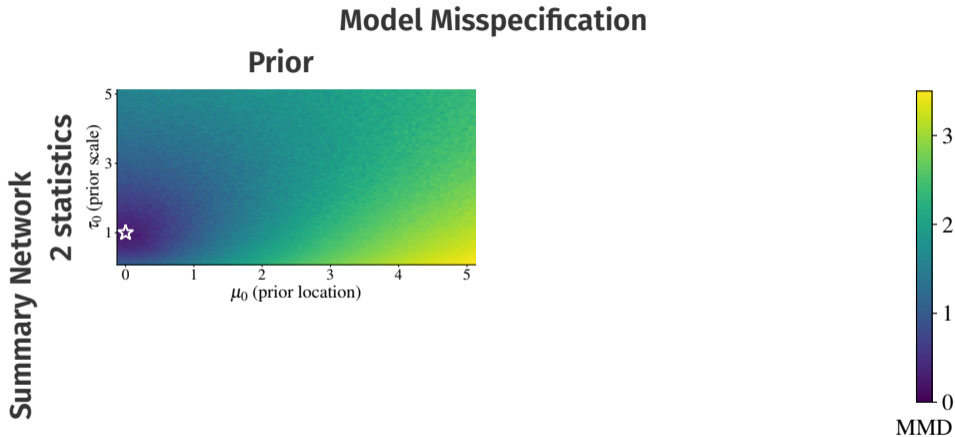
■ No MMS



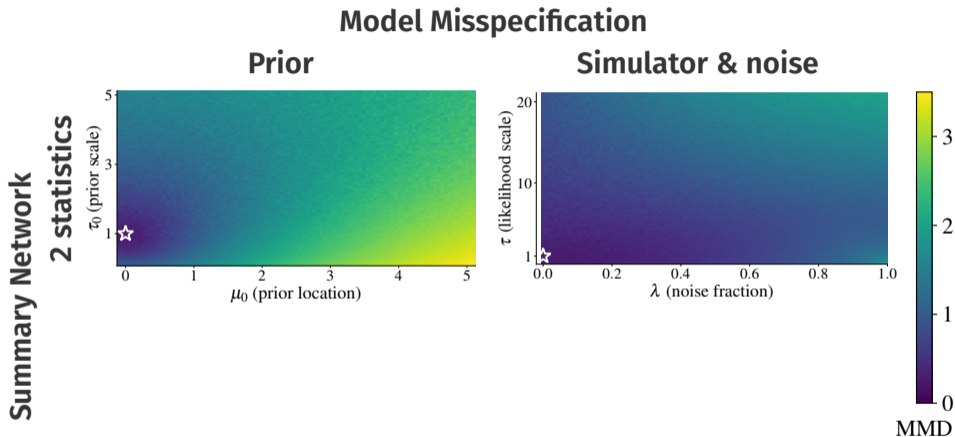
■ Simulator scale: $\tau = 10$

■ Noise fraction: $\lambda = 0.5$

Gaussian: How many summary statistics?

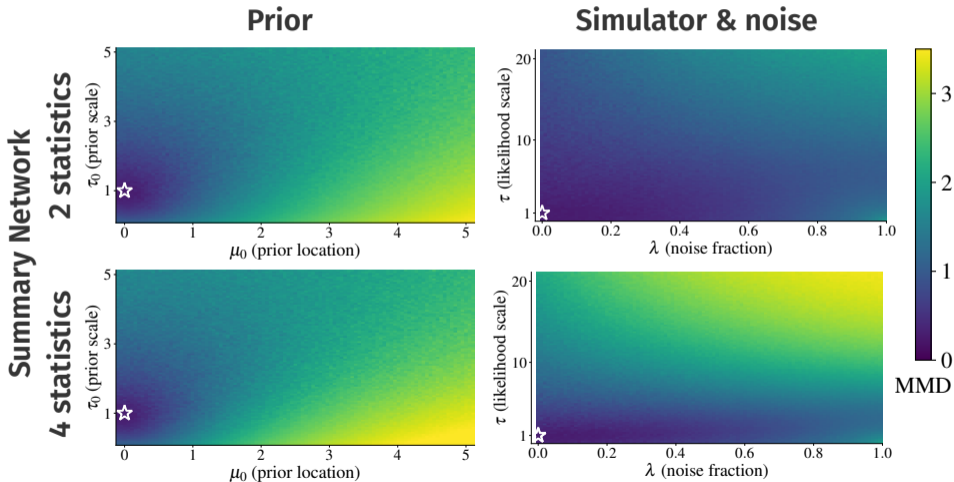


Gaussian: How many summary statistics?



Gaussian: How many summary statistics?

Model Misspecification

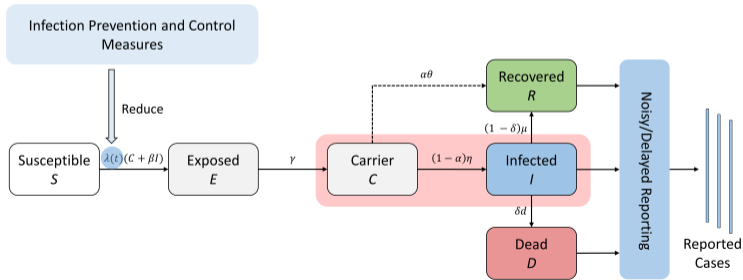


Experiment 3: COVID-19 modeling

COVID-19: Motivation

Compartmental Models for disease outbreaks (Radev et al., 2021)

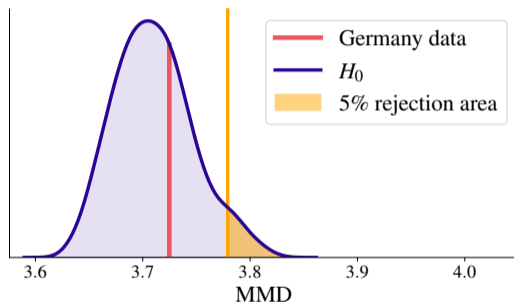
1. Inference is based on posteriors \rightarrow must be trustworthy
2. Are initially well-specified models misspecified at some point?



- Train the network on data from the full model \mathcal{M}^*
- Simulate 1000 time series each from
 - \mathcal{M}^* : full model
 - \mathcal{M}_1 : no intervention sub-model
 - \mathcal{M}_2 : no observation sub-model
- Find discrepancies in the latent summary space

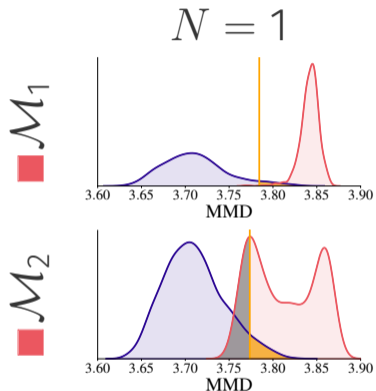
COVID-19: Is the model well-specified for German data?

Frequentist hypothesis test: $H_0 : p^*(\mathbf{x}) = p(\mathbf{x})$ $H_1 : p^*(\mathbf{x}) \neq p(\mathbf{x})$



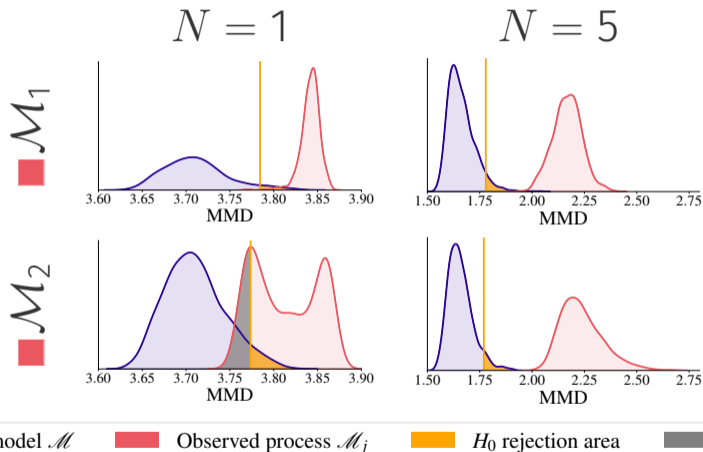
Conclusion: Don't reject the null hypothesis \rightarrow model is well-specified.

Power of a frequentist hypothesis test on summary space MMD



■ Training model \mathcal{M} ■ Observed process \mathcal{M}_j ■ H_0 rejection area ■ Type II (β) error

Power of a frequentist hypothesis test on summary space MMD



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- OOD detection is difficult in data space (entire ML field)

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- Unhappy with MMD or the frequentist hypothesis test?
 - Bring your own distance metric
 - Bring your own test

Summary

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- OOD detection is difficult in data space (entire ML field)
- OOD detection is easier in a structured summary space
- Imposing structure is easy in NPE with learned summaries
- Unhappy with MMD or the frequentist hypothesis test?
 - Bring your own distance metric
 - Bring your own test
- All implementations in the *BayesFlow* library: bayesflow.org

Contact



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