

Towards Reliable Amortized Bayesian Inference

Marvin Schmitt
University of Stuttgart, Germany

 @MarvinSchmittML
 www.marvinschmitt.com

Focus of this talk:

Data-Efficient Learning via Self-Consistency Losses

Extended abstract, NeurIPS UniReps workshop: arxiv.org/abs/2310.04395

Joint work with



Desi Ivanova
Oxford, UK



Daniel Habermann
Dortmund, GER



Ullrich Köthe
Heidelberg, GER

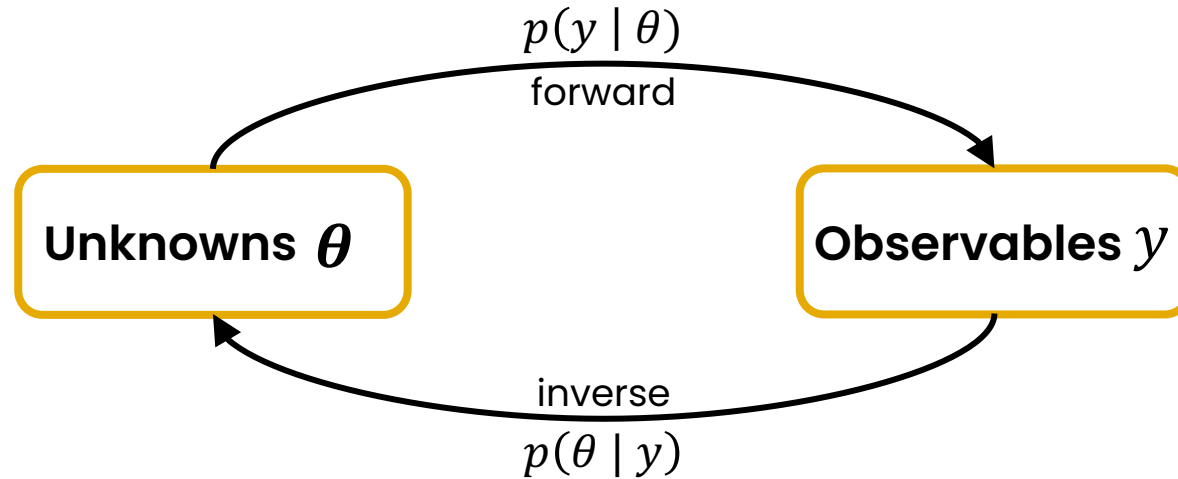


Paul Bürkner
Dortmund, GER



Stefan Radev
RPI, US

Inverse Problems



Statistical modeling: **Parameters θ**

Data y

Epidemiology: Virus attributes

Infection curve (time series)

Image processing: Crisp image

Blurry image

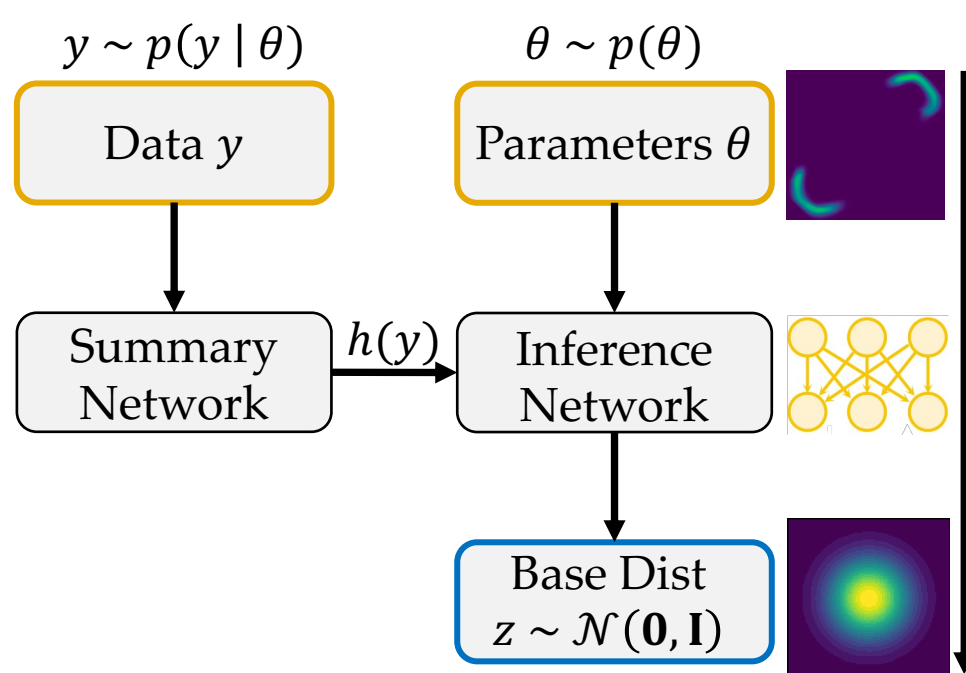
Psychology: Cognitive parameters

Reaction times

Amortized Bayesian inference

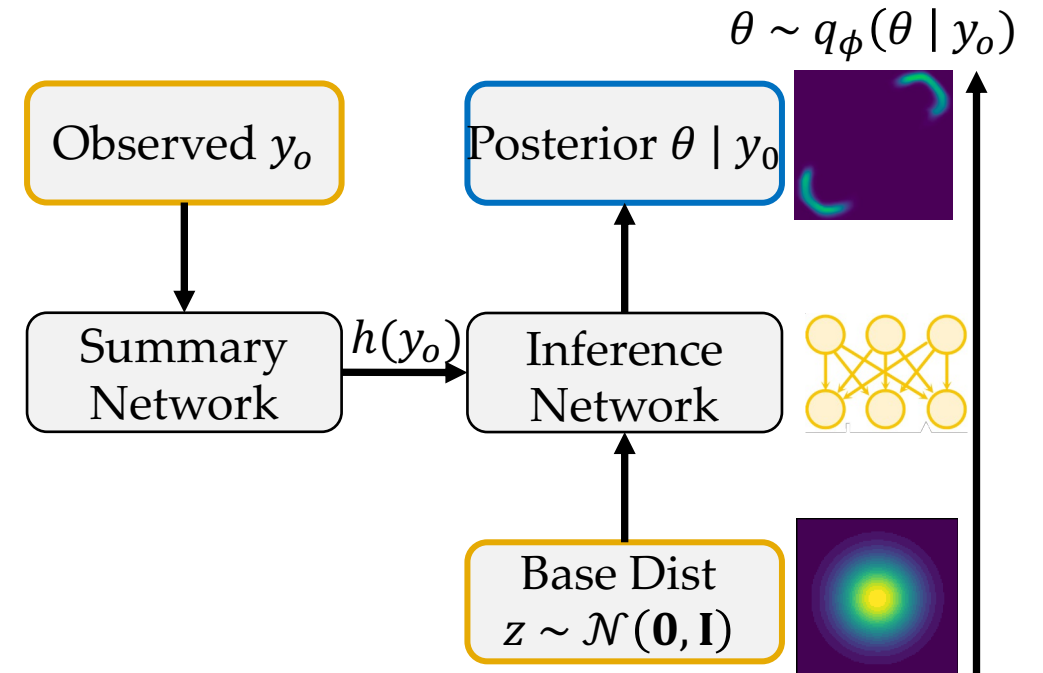
Stage 1: Training (Approximation)

potentially expensive



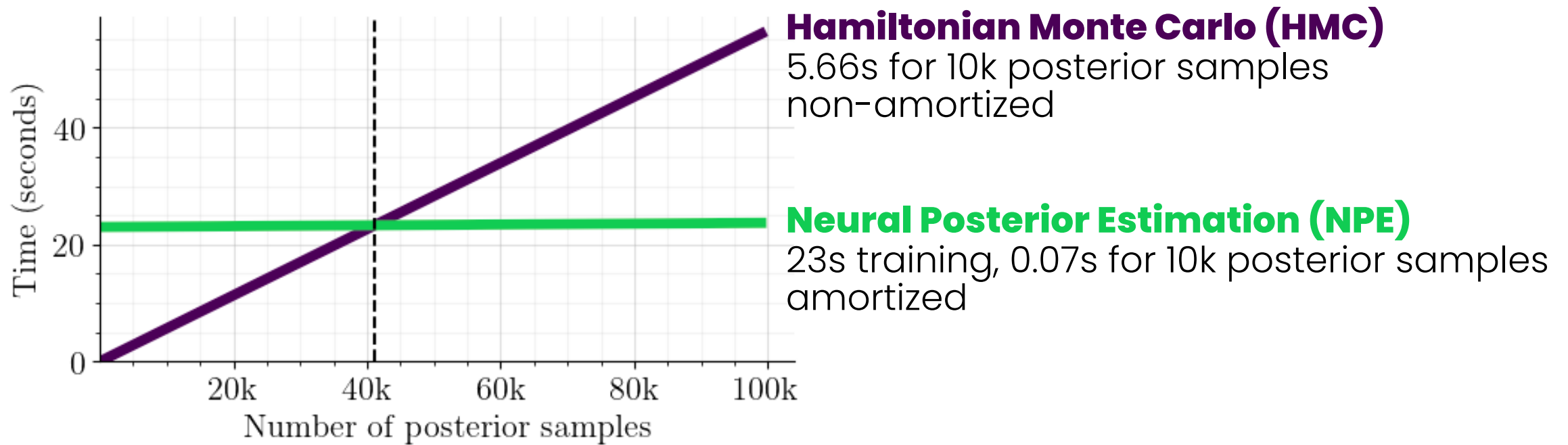
Stage 2: Inference

amortized over many data sets y_o



Approximation and inference are **decoupled**. Pooling of resources.

Potential of Amortized Bayesian Inference



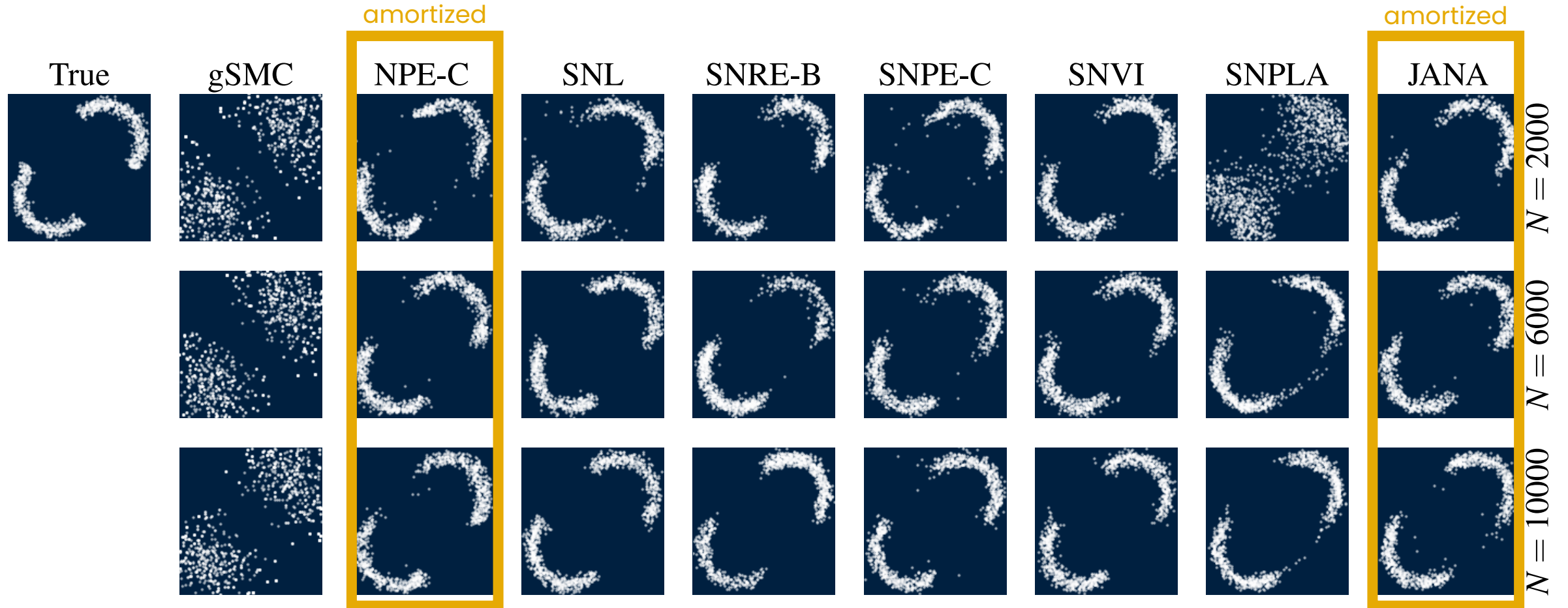
(1) Many model re-fits

- Cross-validation
- Many data sets
- Sensitivity analyses

(2) Real-time inference

- Neurological monitoring
- Adaptive experimental design
- Disease surveillance

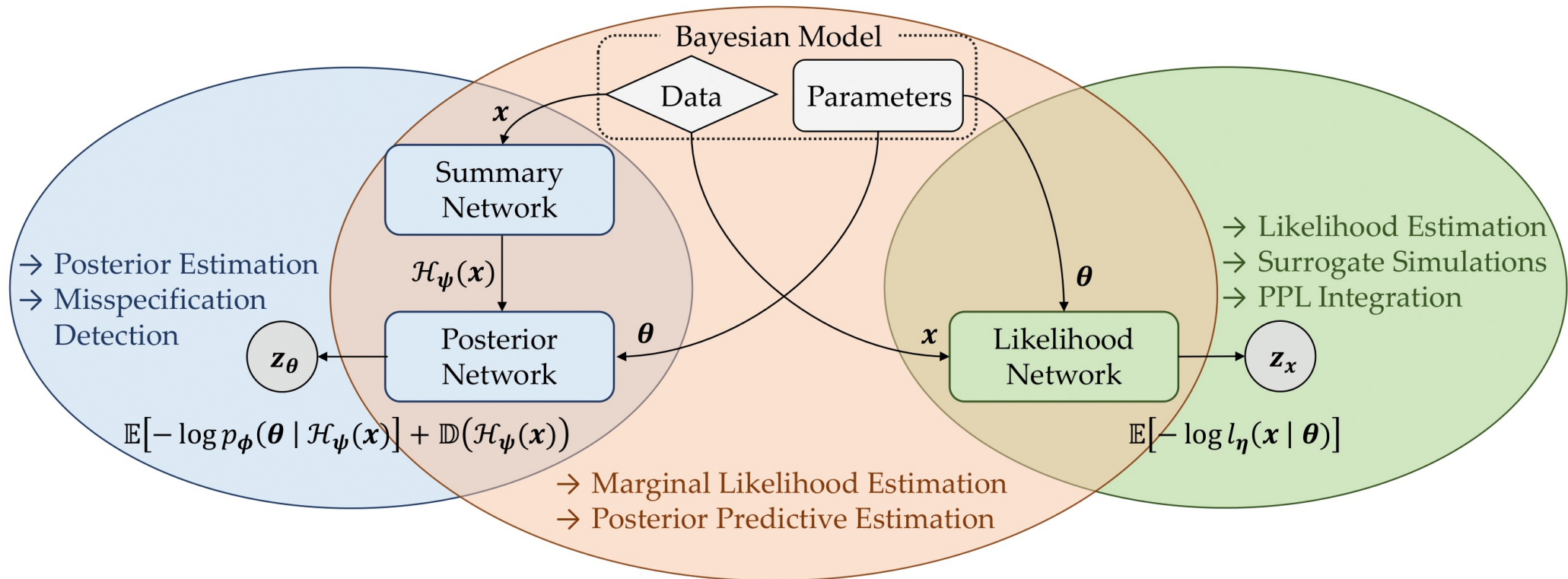
Isn't amortized inference wasteful? **No!**



Amortized methods perform on-par with non-amortized counterparts!

Jointly amortized learning: Posterior + Likelihood

- Jointly amortized neural approximation (JANA; Radev et al., 2023)



Problems of vanilla Amortized Bayesian Inference

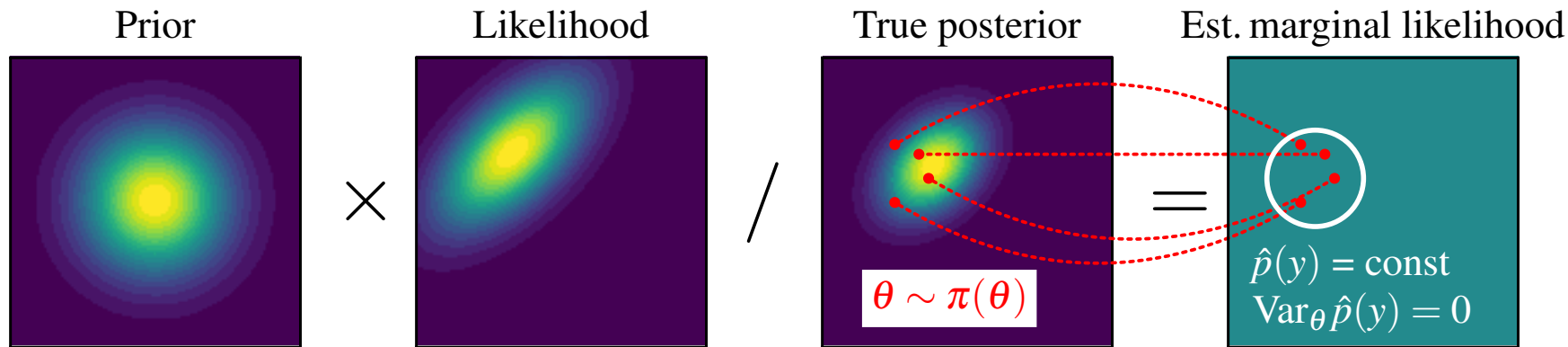
- Neural networks have a bad user experience
- Model misspecification invalidates training
- Normalizing flows restrict network architecture
- Simulation-based training requires lots of training data

Self-consistency criterion

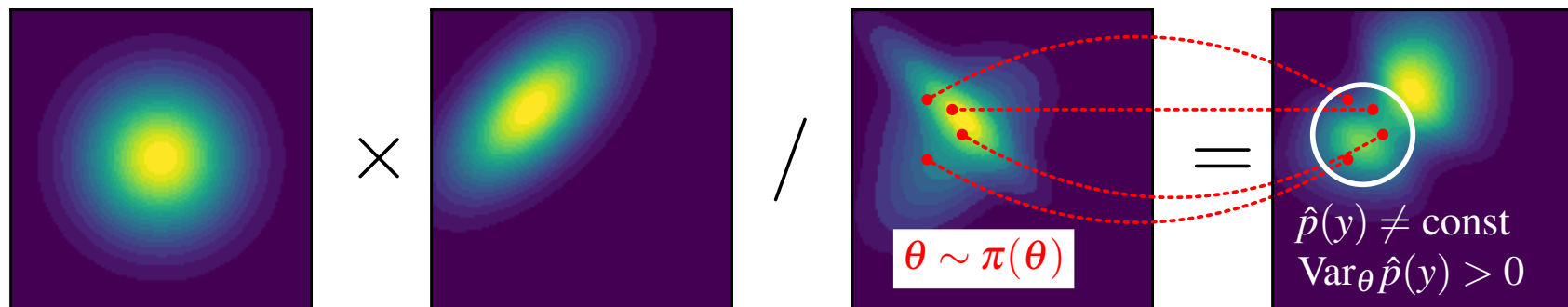
$$p(\boldsymbol{\theta} | \mathbf{Y}) = \frac{p(\boldsymbol{\theta}) p(\mathbf{Y} | \boldsymbol{\theta})}{p(\mathbf{Y})} \iff p(\mathbf{Y}) = \frac{p(\boldsymbol{\theta}) p(\mathbf{Y} | \boldsymbol{\theta})}{p(\boldsymbol{\theta} | \mathbf{Y})} \implies \frac{p(\boldsymbol{\theta}_1) p(\mathbf{Y} | \boldsymbol{\theta}_1)}{p(\boldsymbol{\theta}_1 | \mathbf{Y})} = \dots = \frac{p(\boldsymbol{\theta}_K) p(\mathbf{Y} | \boldsymbol{\theta}_K)}{p(\boldsymbol{\theta}_K | \mathbf{Y})}$$

$\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_K \in \Theta$

Perfect
Symmetry



Approximate
Posterior



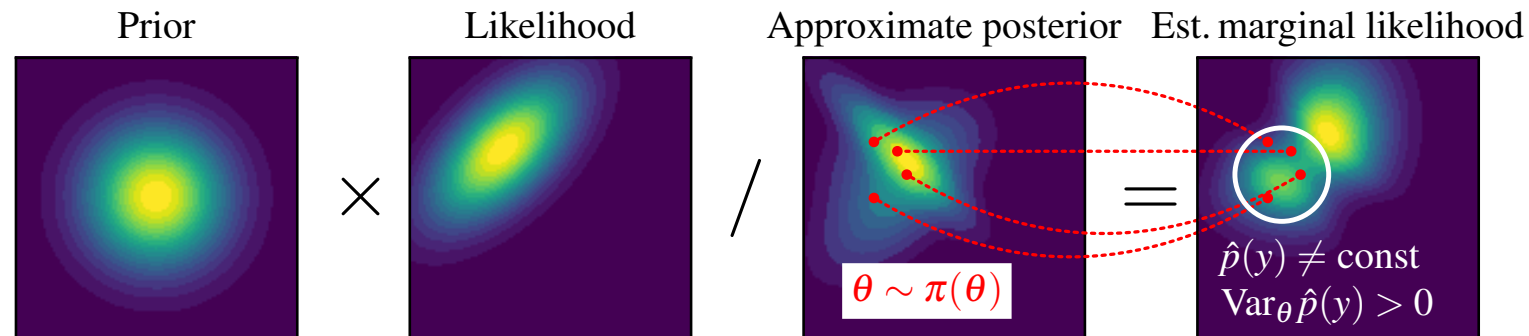
Self-consistency loss

- Idea: Violations of self-consistency property as loss function

$$\mathcal{L}_{\text{SC}}(\mathbf{Y}, \phi) = \text{Var}_{\pi(\theta)} \left(\log \frac{p(\theta) p(\mathbf{Y} | \theta)}{q_{\phi}(\theta | \mathbf{Y})} \right)$$

- Integration into standard neural posterior estimation loss

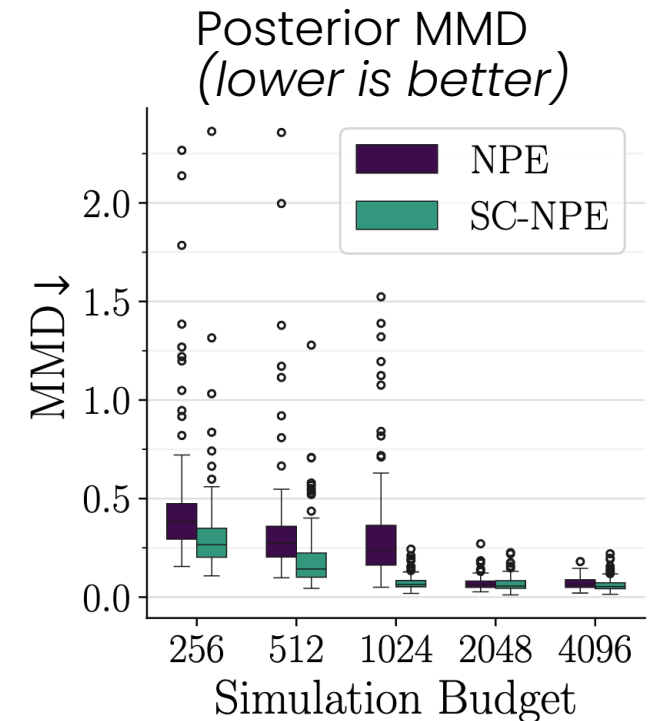
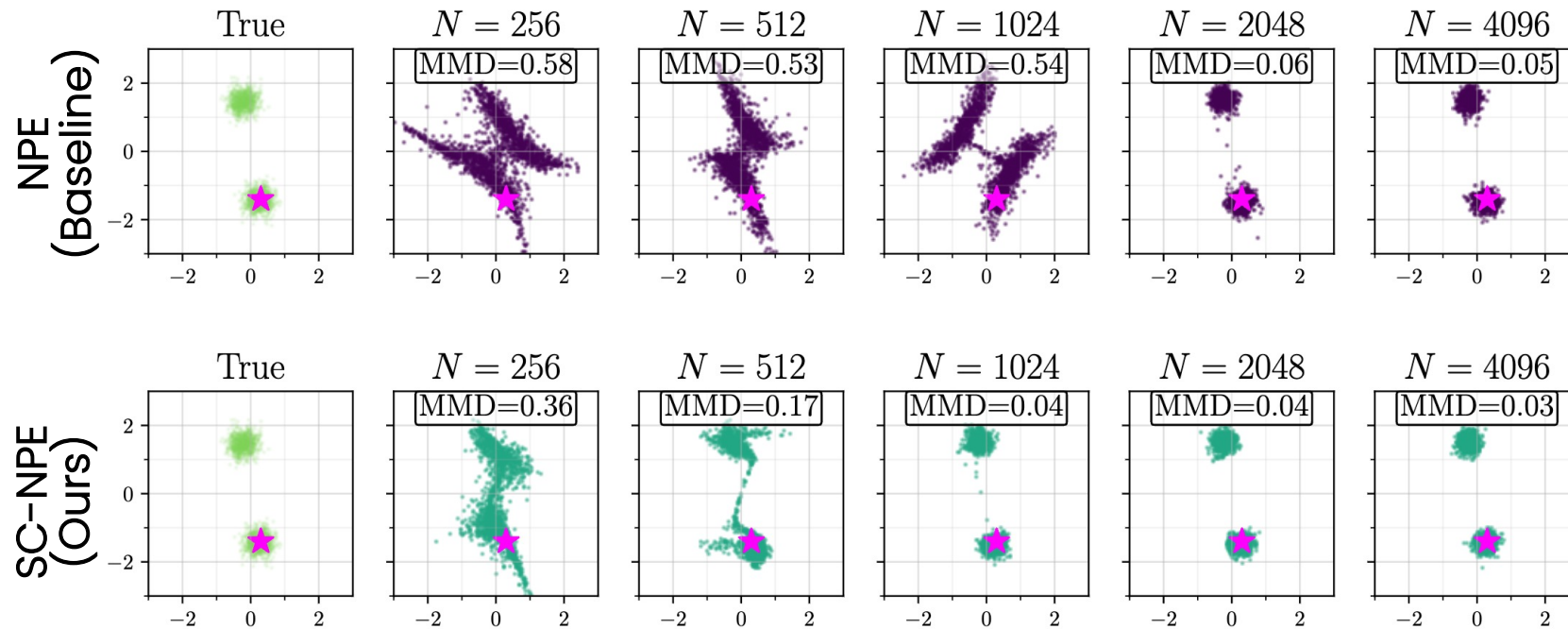
$$\mathcal{L}_{\text{SC-NPE}}(\phi) = \mathbb{E}_{p(\mathbf{Y})} \left[\underbrace{\mathbb{E}_{p(\theta | \mathbf{Y})} [-\log q_{\phi}(\theta | \mathbf{Y})]}_{\text{NPE loss (on fixed } \mathbf{Y})} + \lambda \underbrace{\text{Var}_{\pi(\theta)} \left(\log \frac{p(\theta) p(\mathbf{Y} | \theta)}{q_{\phi}(\theta | \mathbf{Y})} \right)}_{\text{self-consistency loss } \mathcal{L}_{\text{SC}} \text{ with weight } \lambda \geq 0} \right]$$



Experiment 1: Gaussian Mixture

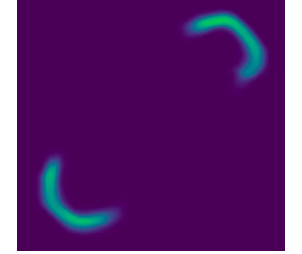
Posterior estimation, varying training budget N

- Model: $\theta \sim \mathcal{N}(\theta | \mathbf{0}, \mathbf{I})$, $y \sim 0.5 \mathcal{N}(y | \theta, \mathbf{I}/2) + 0.5 \mathcal{N}(y | -\theta, \mathbf{I}/2)$
- Results: Better posterior samples compared to vanilla NPE

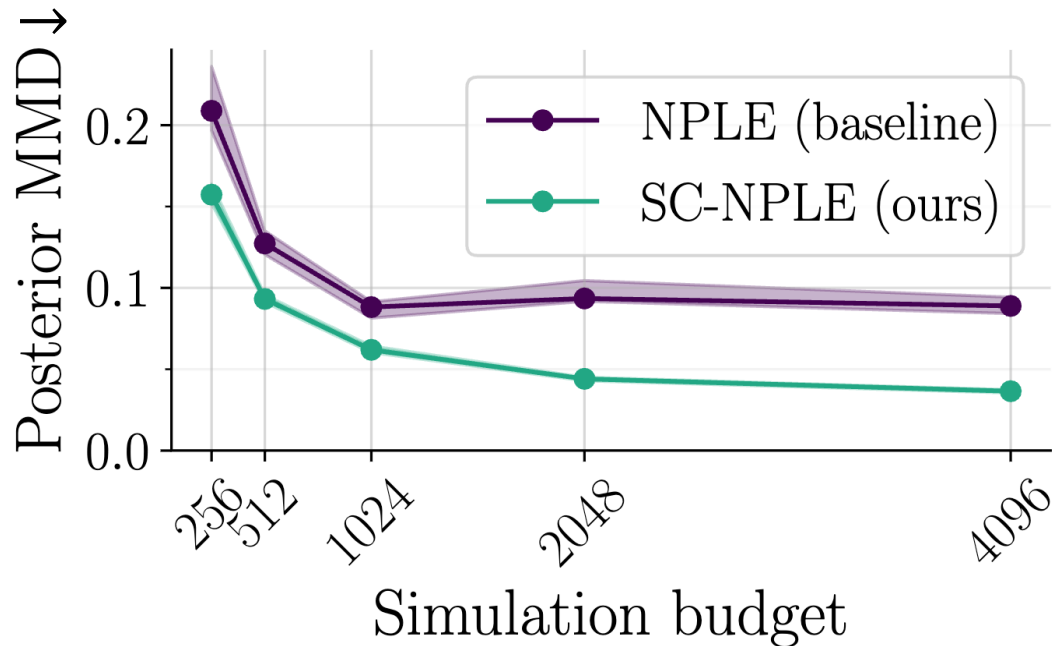


Experiment 2: Two Moons

Posterior and likelihood estimation, varying training budget N



(1) Better posterior samples
(MMD, lower is better)



(2) Sharper log marginal likelihood

Method	$N=512$	$N=1024$	$N=2048$	$N=4096$
NPLE	6.51 ± 0.11	7.28 ± 0.10	9.07 ± 0.06	10.21 ± 0.08
SC-NPLE	1.70 ± 0.02	1.37 ± 0.02	1.21 ± 0.01	1.14 ± 0.01

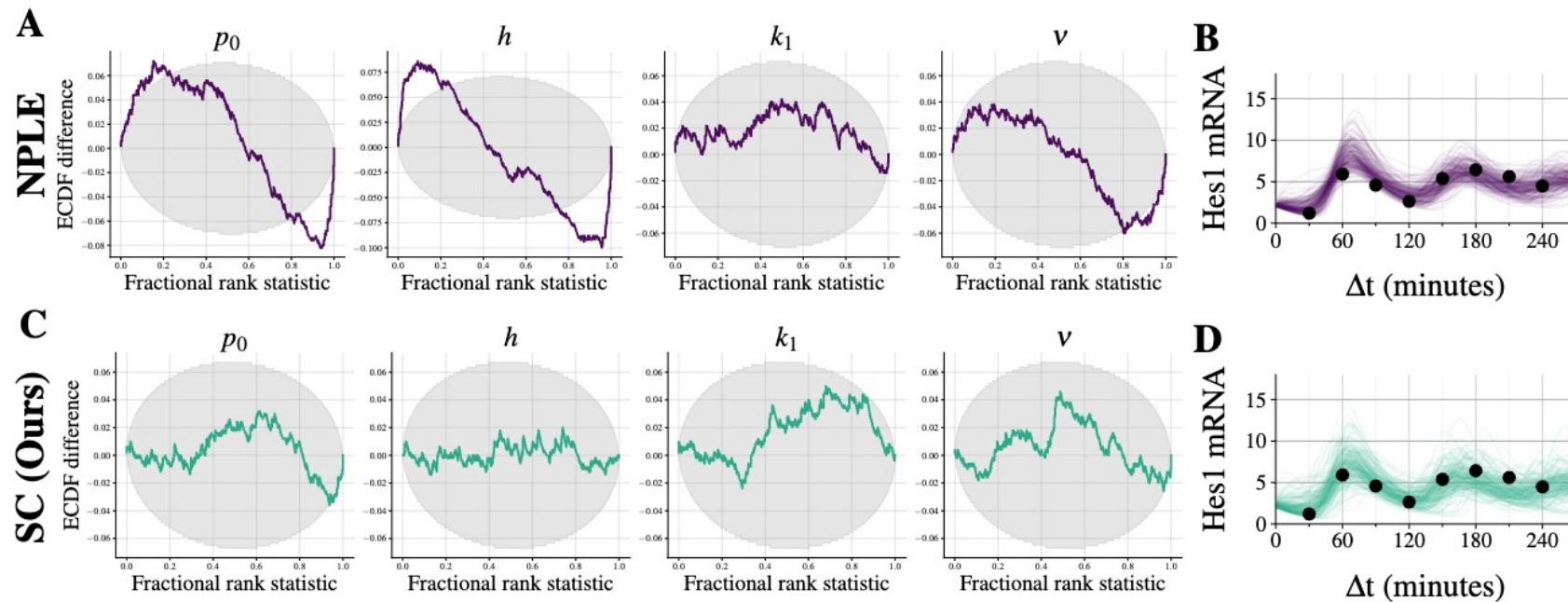
Width of 95% CI of the LML for a data set, mean \pm SE

Experiment 3: Hes1 Expression Model

Posterior and likelihood estimation, $N = 512$ training budget

Results compared to NPLE baseline:

- Better simulation-based calibration (SBC; Talts et al., 2018)
- Similar posterior predictive results



Summary and Outlook

Self-consistency losses reward consistent marginal likelihood estimation

Gains:

- Improved neural **posterior** estimation (SC-NPE)
- Improved neural **likelihood** estimation (SC-NPLE)
- Improved neural **marginal likelihood** estimation (SC-NPLE)
- Direct extension to popular loss functions in amortized inference

Limitations:

- More expensive upfront **training** → later break-even with non-amortized
- More **hyperparameters** → develop automated choices

Acknowledgments and Contact

Thanks to my supportive colleagues and advisors:

- Paul Bürkner, TU Dortmund University, Germany, paul-buerkner.github.io
- Stefan Radev, Rensselaer Polytechnic Institute, US, faculty.rpi.edu/stefan-radev
- all BayesFlow contributors: www.BayesFlow.org

Partially funded by:



CONTACT



@MarvinSchmittML



www.marvinschmitt.com

I am on the job market for winter 2024. Let's chat!